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| EC | Impact of spectral covariance on line fitting | Ref.: | EUCL-IPN-TN-8-001 |
| | | Issue: | Draft 0.2 |
| | | Date: | 09/12/2014 |
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| Title: | Impact of spectral covariance on line fitting | | |
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| Reference: | EUCL-IPN-TN-8-001 | | |
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Document version tracking

| Issue | Date | Page | Description of changes | Comments |
|-----------|------------|------|------------------------------------|----------|
| Draft 0.1 | 25/04/2014 | 1 | Initial import from personal note. | |
| Draft 0.2 | 09/12/2014 | 1 | Typos, font management. | |

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1 Purpose

I look for the impact of the spectral covariance on the line fitting procedure. It appears that the maximum-likelihood estimates — for all line parameters — are equally *unbiased* when using the correct full-covariance χ^2 definition and the simpler pure-diagonal one (i.e. neglecting spectral correlations). However, best-fit parameter uncertainties — on line flux, position/*redshift* and width — are systematically *under-estimated* by $\sim 40\%$ when using the uncorrelated χ^2 , while properly estimated when minimizing the statistically correct χ^2 . The use of spectral covariance is therefore of crucial importance to derive statistically controlled spectral quantities such as redshift and line fluxes.

2 Scope

Spectral measurements in OU-SPE.

3 Applicable & Reference documents

3.1 Applicable documents

| RD | Ref. | Date |
|----|------|------|
| | | |

3.2 Reference documents

| RD | Ref. | Date |
|----|------|------|
| | | |

4 Acronyms

| | |
|-----|---------------------------|
| MAD | Median Absolute Deviation |
| ML | Maximum Likelihood |
| SNR | Signal-to-Noise Ratio |

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5 Data simulation

5.1 Intrinsic signal

The *true* simulated spectrum $S(a, \mu, \sigma) = (S_1, \dots, S_N)$ ($N = 32$ in this analysis) is a single Gaussian emission line, characterized by its peak amplitude $a > 0$, its mean position μ and dispersion σ (in pixel units), on a constant null continuum:

$$S_i(a, \mu, \sigma) = a \exp\left(-\frac{(i - \mu)^2}{2\sigma^2}\right). \quad (1)$$

5.2 Intrinsic (co)variance

The signal is simulated in the regime of *constant* normal noise¹, and the flux units are chosen such that:

$$\sigma_i = 1, \quad i = 1, \dots, N. \quad (2)$$

The amplitude a of the emission line is therefore directly representative of its (peak) signal-to-noise ratio (SNR).

To account for *short-scale* correlations between adjacent pixels in the simulated spectrum, the intrinsic covariance matrix Σ is chosen to follow an isotropic exponential covariance function, of scale-length $\tau \geq 0$:

$$\Sigma_{ij}(\tau) = \begin{cases} \sigma_i \sigma_j \exp\left(-\frac{|i-j|}{\tau}\right) & \text{if } \tau > 0, \\ \sigma_i \sigma_j \delta_{ij} & \text{if } \tau = 0. \end{cases} \quad (3)$$

The limit case $\tau = 0$ corresponds to a purely diagonal covariance matrix, i.e. to the absence of correlations.

5.3 Simulated signal

A signal simulation \mathbf{y} is the sum of the intrinsic signal $S(a, \mu, \sigma)$ and a realization of the noise $\epsilon(\tau)$ with the desired correlation:

$$y_i = S_i(a, \mu, \sigma) + \epsilon_i(\tau). \quad (4)$$

Intrinsic signals will be generated using the following input parameters:

- $a = 2$ (low SNR regime), 5, 10 and 20 (high SNR regime);
- Input μ is a random variable uniformly distributed in ± 1 px, to avoid any systematic sampling effect. The quoted line position is actually the offset $\delta\mu = \hat{\mu} - \mu$, where $\hat{\mu}$ is the adjusted position;
- $\sigma = 1$ (barely sampled line), 2 and 3 px (over-sampled line).

For this analysis, I initially generate $L = 1000$ *uncorrelated* noise realizations $\mathbf{n} = (n_1, \dots, n_L)$ from normal distribution $\mathcal{N}(\mu = 0, \sigma^2 = 1)$. These uncorrelated noise realizations are then spectrally correlated using the targeted covariance matrix $\Sigma(\tau)$ (Eq. (3)) to produce to noise realizations $\epsilon(\tau)$ with the desired correlation length τ :

- $\tau = 0$ (no correlation), 2 px and 5 px (strong spectral correlation²).

This procedure ensures that all simulated signals share the same noise realizations up to the spectral correlation (see Fig. 1): one can then directly estimate the impact of the covariance in the adjustment of the simulated spectra.

¹This is valid if the spectral background flux per pixel — e.g. from zodiacal light — is high enough to ensure noise normality.

²The case $\tau = 2$ px corresponds to a correlation coefficient of $\rho = e^{-1/2} = 60\%$ between adjacent pixels, while $\tau = 5$ px gives $\rho = 82\%$.

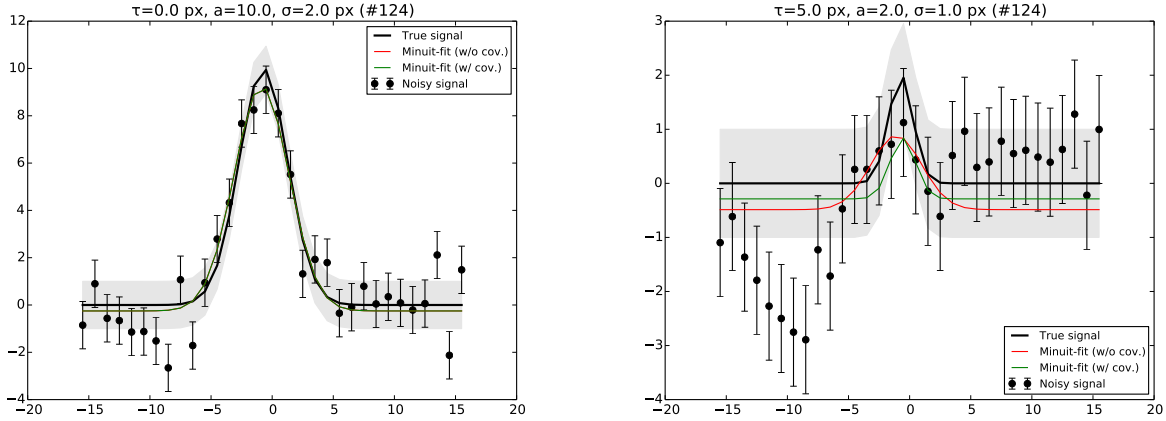


Figure 1: Example of simulated signals. *Left*: $a = 10$, $\mu = -0.71$ px and $\sigma = 2$ px, no inter-pixel correlation ($\tau = 0$); *right*: $a = 2$, $\mu = -0.71$ px and $\sigma = 1$ px, with a correlation length of $\tau = 5$ px. The two simulated signals share the same uncorrelated noise realization. The true signal and uncertainty $S \pm \sigma$ is represented by the *heavy line* \pm *shaded area*; the actual simulated spectrum $y \pm \sigma$ is represented by *black symbols* \pm *error bars*. The results of the adjustments using full-covariance χ^2_{Cov} (Eq. (7)) or pure-diagonal χ^2_{σ} (Eq. (9)) are displayed by the *green* and *red* lines respectively (they are naturally combined in the uncorrelated case).

6 χ^2 minimization

Since noise realizations are purely Gaussian, the maximum-likelihood (ML) parameters $\hat{\theta}$ can be estimated from minimization of the χ^2 objective function comparing the observed signal \mathbf{y} to the model $\mathbf{F}(\theta)$:

$$\hat{\theta} = \operatorname{argmin} \chi^2(\mathbf{y} - \mathbf{F}(\theta)). \quad (5)$$

The minimization will be performed using the `mingrad` minimizer from the `Minuit` library, through the `pyminuit` interface.

6.1 Model

The adjusted model $\mathbf{F}(f, \mu, \sigma, b)$ is a Gaussian profile on a constant background b :

$$F_i(f, \mu, \sigma, b) = \frac{f}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(i - \mu)^2}{2\sigma^2}\right) + b. \quad (6)$$

I choose here to adjust for the physically-motivated *integrated* flux f of the line, not its peak amplitude $a = f/\sqrt{2\pi}\sigma$. Note furthermore that the model does not account for pixel-integration, and therefore is expected to poorly perform on under-sampled lines ($\sigma \lesssim 1$).

6.2 Objective functions

The objective of the analysis is to estimate the impact of the covariance use in the adjustment of spectrally correlated spectra. I therefore compare the parameters estimated by minimizing two different χ^2 objective functions:

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Full-covariance: the proper χ^2 definition is presence of a covariance matrix V between the measurements \mathbf{y} (i.e. $V_{ij} = \text{Cov}(y_i, y_j)$) is:

$$\chi_{\text{Cov}}^2(\boldsymbol{\theta}) = (\mathbf{y} - \mathbf{F}(\boldsymbol{\theta}))^T \cdot V^{-1} \cdot (\mathbf{y} - \mathbf{F}(\boldsymbol{\theta})). \quad (7)$$

In the present analysis, the covariance matrix V of simulated observations \mathbf{y} is — rather optimistically — set equal to the intrinsic covariance Σ :

$$V = \Sigma. \quad (8)$$

Pure-diagonal: when neglecting the off-diagonal terms of the covariance, the previous expression only depends on the diagonal terms, i.e. variances σ_i^2 :

$$\chi_{\sigma}^2(\boldsymbol{\theta}) = \sum_{i=1}^N \frac{(y_i - F_i(\boldsymbol{\theta}))^2}{\sigma_i^2}. \quad (9)$$

Both objective functions supposedly follow a χ^2 -distribution with $k = N - M$ degrees of freedom, where $M = 4$ is the number of adjusted parameters.

7 Results

For each $\boldsymbol{\theta} = (a, \mu, \sigma)$ input parameter set and noise correlation length τ , a dataset of $L = 1000$ simulated spectra is generated (all sharing the same uncorrelated noise realizations), and ML parameters $\hat{\boldsymbol{\theta}}$ are estimated independently from minimization of:

1. the full-covariance χ_{Cov}^2 (Eq. (7)),
2. the pure-diagonal χ_{σ}^2 (Eq. (9)).

I use the “pull” distribution, defined as:

$$p_j = \frac{\hat{\alpha}_j - \alpha}{\sigma_{\hat{\alpha}_j}}, \quad j = 1, \dots, L, \quad (10)$$

where $\hat{\alpha}_j$ (resp. $\sigma_{\hat{\alpha}_j}$) is the ML estimate (resp. the estimated uncertainty) of “true” parameter α . This pull distribution has the following interesting properties:

- its mean value $\mu_p = 0$ if the parameter estimator is *unbiased*;
- its standard error $\sigma_p = 1$ if the parameter uncertainty estimate $\sigma_{\hat{\alpha}}$ is correct³: $\sigma_p > 1$ (resp. < 1) means that the parameter uncertainty $\sigma_{\hat{\alpha}}$ has been *under-estimated* (resp. *over-estimated*) by a factor $1/\sigma_p$;
- the pull $\chi_p^2 = \sum_{j=1}^L p_j^2$ follows a χ^2 distribution with L degrees of freedom, and a goodness-of-fit (actually a parameter estimate reliability) can be estimated from its associated one-tail p -value⁴.

Statistics of the adjusted parameters $\hat{\boldsymbol{\theta}}$ for the test-case $a = 10$, $\sigma = 2$ px (resulting in an input flux of $f = a\sqrt{2\pi}\sigma = 50.13$) in the moderately correlated case (correlation length of $\tau = 2$ px) are presented in Table 4:

- mean and standard deviation of parameter estimates,
- median and normalized median absolute deviation (nMAD) of parameter estimates,
- pull χ_p^2 — which follows a χ^2 distribution with $L = 1000$ degrees of freedom — and associated p -value,
- mean and standard deviation of pull distribution.

As can be seen from Table 4:

³In presence of a bias, $\sigma_p^2 = 1 + \mu_p^2$.

⁴This is the probability for the χ^2 to reach such a high value assuming the description of the distribution is correct.

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Table 4: Results for the moderately correlated case ($\tau = 2$ px), with $a = 10$ and $\sigma = 2$ px (i.e. $f = 50.13$). The pull χ_p^2 has $L = 1000$ degrees of freedom, its associated p -value is quoted in percents.

| Parameter | Parameter distribution | | | | Pull distribution | | | |
|--------------------------------|------------------------|----------|---------|-------|-------------------|---------|---------|------------|
| | μ | σ | Med | nMAD | χ_p^2 | p [%] | μ_p | σ_p |
| Pure-diagonal χ_σ^2 | | | | | | | | |
| f | +50.923 | 7.236 | +50.449 | 7.507 | 3117 | 0 | +0.070 | 1.765 |
| $\delta\mu$ | +0.001 | 0.218 | +0.002 | 0.208 | 2003 | 0 | +0.006 | 1.416 |
| σ | +2.015 | 0.227 | +1.996 | 0.214 | 1706 | 0 | -0.051 | 1.306 |
| b | -0.034 | 0.405 | -0.044 | 0.401 | 3459 | 0 | -0.133 | 1.856 |
| Full-covariance χ_{Cov}^2 | | | | | | | | |
| f | +50.611 | 6.837 | +50.134 | 7.015 | 1083 | 3 | +0.010 | 1.041 |
| $\delta\mu$ | -0.001 | 0.197 | +0.000 | 0.195 | 1008 | 42 | -0.001 | 1.005 |
| σ | +1.997 | 0.198 | +1.984 | 0.193 | 1119 | 1 | -0.133 | 1.050 |
| b | -0.024 | 0.396 | -0.033 | 0.397 | 1036 | 21 | -0.054 | 1.017 |

- $\mu_p \simeq 0$: none of the ML estimates is strongly biased, using the exact full-covariance χ_{Cov}^2 definition or the simpler pure-diagonal χ_σ^2 one;
- $\sigma_{p,Cov} \simeq 1$: the uncertainties of the ML estimates are correct when using the full-covariance χ_{Cov}^2 definition;
- $\sigma_{p,\sigma} > 1$: the uncertainties of the ML estimates are systematically *under*-estimated when using the pure-diagonal χ_σ^2 definition: the line flux error $\sigma_{\hat{f}}$ is under-estimated by 43%, the position error $\sigma_{\hat{\mu}}$ by 29%, and the line width error $\sigma_{\hat{\sigma}}$ by 23%.

The ML estimate distributions as well as the associated pull distributions are presented in Fig. 2 for the moderately correlated case ($\tau = 2$ px). Once again, it becomes apparent that while the ML parameter estimate are barely sensitive to the use or not of the full-covariance matrix, the uncertainties on ML estimates are systematically *under*-estimated by up to $\sim 40\%$ when using pure-diagonal χ_σ^2 .

Fig. 3 shows the evolution of pull mean μ_p and standard deviation σ_p for different parameters as function of correlation length τ for the test-case $a = 10$, $\sigma = 2$ px. The error on the ML estimate uncertainty presumably increases steadily with τ for background level (b) and line flux (f , the two parameters being strongly correlated). On the other hand, the error on the ML estimate uncertainty of line position μ and width σ probably peaks when $\tau \sim \sigma$. This evolution with τ has to be confirmed by more exhaustive simulations.

8 Conclusions

I generated intrinsic Gaussian emission line spectra with different reasonable input parameters (peak amplitude a , mean position $\mu \simeq 0$, line width σ), and added noise realizations under the assumption of constant normal noise and varying correlation length τ .

Maximum-likelihood parameter estimates were obtained by minimizing two versions of the χ^2 :

- the full-covariance χ_{Cov}^2 , taking full account of the (supposedly known) covariance matrix;
- the pure-diagonal χ_σ^2 , neglecting all off-diagonal terms (i.e. correlations) of the covariance matrix.

It appears from the pull distribution analyzes that:

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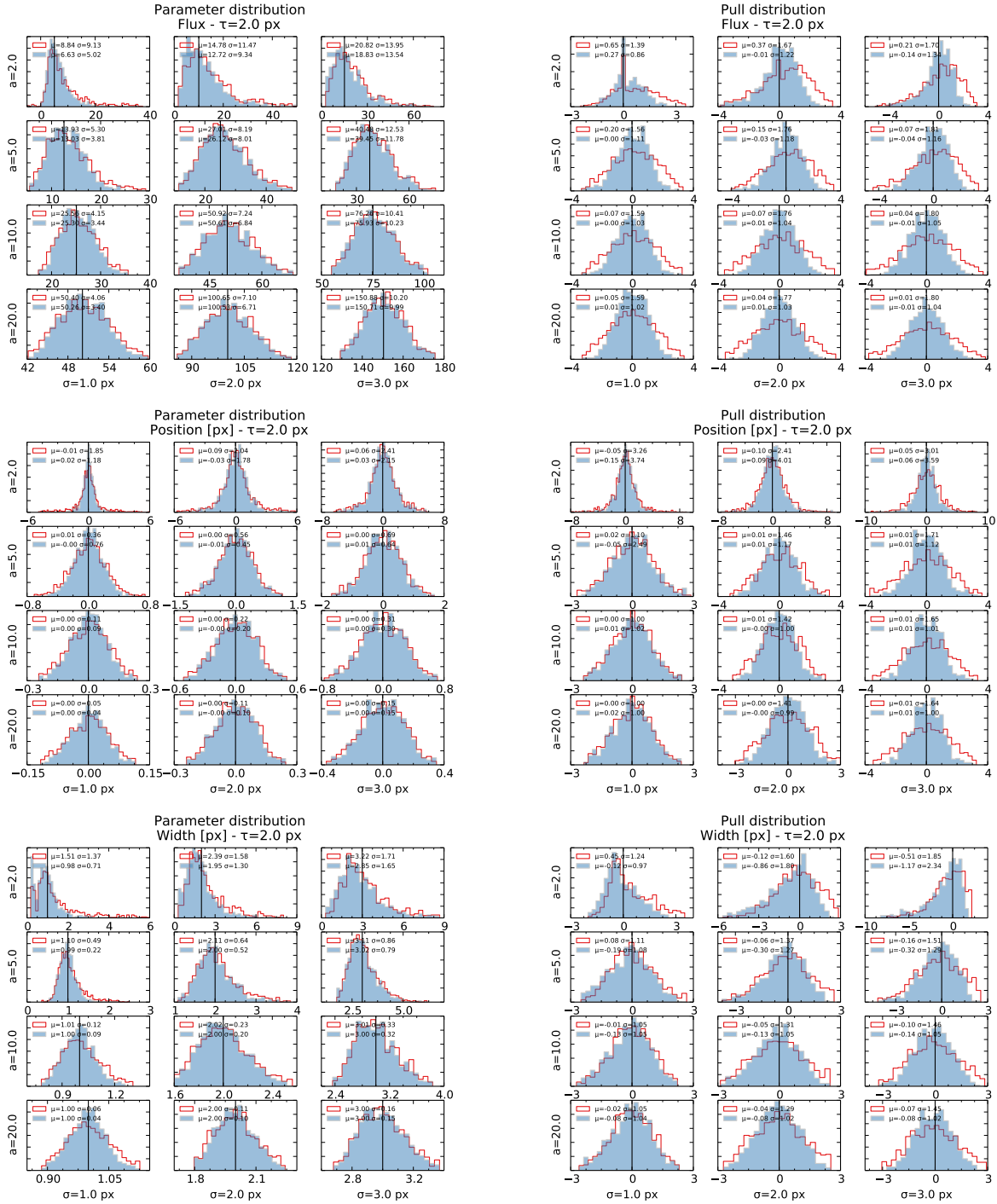


Figure 2: Results for the moderately correlated case ($\tau = 2$ px). *Left column:* parameter distribution (from top to bottom: flux f , position offset $\delta\mu$ and line width σ), when using full-covariance χ^2_{Cov} (Eq. (7), shaded blue) in the line fit, or pure-diagonal χ^2_{σ} (Eq. (9), red line). *Right:* pull distributions.

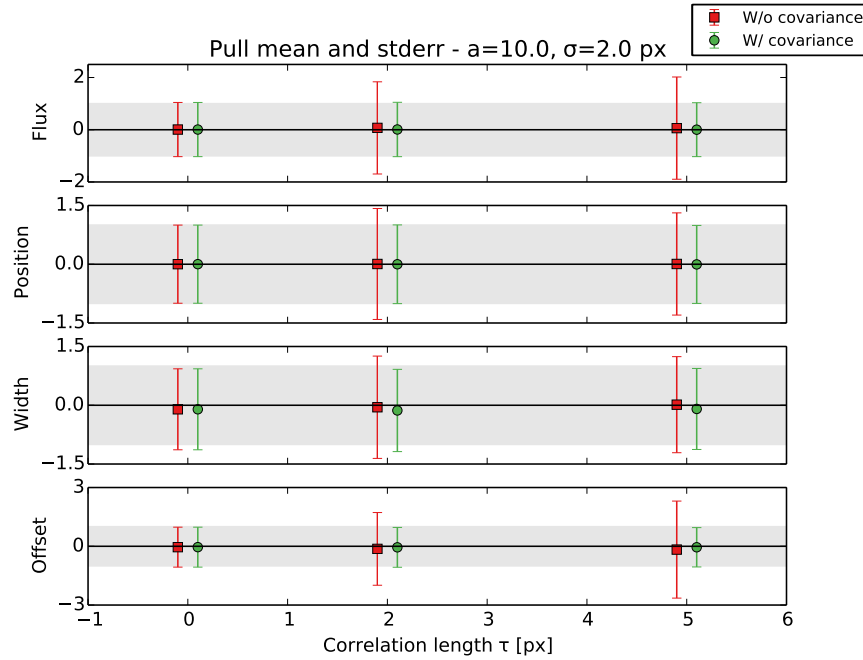


Figure 3: Evolution of pull mean and standard error as a function of correlation length τ for test-case $a = 10$ and $\sigma = 2$ px (i.e. $f = 50.13$), when using pure-diagonal χ_{σ}^2 (Eq. (9), red symbols) or full-covariance χ_{Cov}^2 (Eq. (7), green symbols) in the line fit. From top to bottom: flux f , position offset $\delta\mu$, line width σ and background level b . The gray shaded area corresponds to the ideal pull range 0 ± 1 .

- the ML estimates — for all line parameters — are equally *unbiased* when using the correct χ_{Cov}^2 definition and the simpler χ_{σ}^2 one;
- the ML estimate uncertainties — on line flux, position/*redshift* and width — are systematically *underestimated* by up to 40% when using the simpler χ_{σ}^2 , while they are correct when minimizing χ_{Cov}^2 ;
- (to be confirmed) when using χ_{σ}^2 , the error on flux uncertainty is increasing with correlation length τ , while error on position/*redshift* and line width peak at $\tau \simeq \sigma$.

The use of the full-covariance χ_{Cov}^2 is therefore of crucial importance to derive statistically controlled spectral quantities such as redshift and line fluxes. This requires the precise knowledge of the spectral covariance properties of the fully-calibrated spectra, either from a proper uncertainty propagation among the successive calibration steps, or from *a posteriori* estimates on observed signals.